
Registration of range-finder and TV data for bulding of 3D environment

© S.N. Zagoroyko, V.P. Noskov

Bauman Moscow State Technical University, Moscow, 105005, Russia

Computer vision systems using RGBD sensors and point cloud registration algorithms are discussed. Mobile robot navigation algorithm using RGB descriptors and dual quaternion rigid transformation estimation is proposed. Experimental results and sensor information are shown.

Keywords: *3d reconstruction, registration, dual quaternion optimization, RGBD sensor, transformation estimation.*

Zagoruiko S.N. (b. 1990) graduated from Bauman Moscow State Technical University in 2013. Post-graduate of the Special Robotics and Mechatronics Department of Bauman Moscow State Technical University. Author of 5 science papers in image processing and computer vision. e-mail: zagoruyko2@gmail.com

Noskov V.P. (b. 1951) graduated from Kalmykov Taganrog Radio-Technical Institute in 1974. Ph.D., Head of Research Institute of Scientific and Educational Complex Special Engineering of Bauman Moscow State Technical University, Assoc. Professor of the Special Robotics and Mechatronics Department. Author of more than 100 science papers in robotics. e-mail: noskov_mstu@mail.ru
