

Controlling the orientation of a polar-orbiting satellite by means of magnetic moments

© V.M. Morozov, V.I. Kalenova

Institute of Mechanics, Lomonosov Moscow State University,
Moscow, 119192, Russia

The article considers the problem of controlling the orientation of a polar-orbiting satellite in a circular orbit by means of magnetic moments. A direct magnetic dipole has been adopted as a model of the geomagnetic field. The system of equations of motion is linearized in a neighborhood of the relative equilibrium position. A system of equations of controlled motion belonging to a special class of linear nonstationary systems, for which there exists a transformation leading these systems to stationary systems of higher dimension, is explicitly indicated. On the basis of the given stationary system, controllability is investigated; efficient algorithms for optimal stabilization of the satellite relative equilibrium position are constructed. For these algorithms the control action is a function of the stationary system variables of a higher order than the initial nonstationary system. To synthesize control directly in the initial system, auxiliary variables are introduced, so as to make the transition from the state vector of the reduced stationary system to the state vector of the initial system, supplemented by auxiliary variables. The results of mathematical simulation of the constructed algorithms confirming the effectiveness of the proposed methodology are presented.

Keywords: *satellite, orientation, magnetic control systems, linear non-stationary systems, reducibility, controllability, stabilization algorithms*

REFERENCES

- [1] Psiaki M.L. *Journal of Guidance, Control, and Dynamics*, 2001, vol. 24, no. 2, pp. 386–304.
- [2] Lovera M., Astolfi A. *IEEE Transactions on Aerospace and Electronic Systems*, 2006, vol. 42, no. 3, pp. 796–805.
- [3] Lovera M., Astolfi A. *ELSEVIER, Automatica*, 2004, vol. 40, no. 8, pp. 1405–1414.
- [4] Silani E., Lovera M. *Control Engineering Practice*, 2005, vol. 13, no. 3, pp. 357–371.
- [5] Giulietti F., Quarta A.A., Tortora P. *Journal of Guidance, Control, and Dynamics*, 2006, vol. 29, no. 6, pp. 1464–1468.
- [6] Cubas J., Farrahi A., Pindado S. *Journal of Guidance, Control, and Dynamics*, 2015, vol. 38, no. 10, pp. 1947–1958.
- [7] De Angelis E., Giulietti F., de Ruiter A.H.J., Avanzini G. *Journal of Guidance, Control, and Dynamics*, 2016, vol. 39, no. 3, pp. 564–573.
- [8] Yaguang Yang. *IEEE Transactions on Aerospace and Electronic Systems*, 2016, vol. 52, no. 2, pp. 955–962.
- [9] Ovchinnikov M.Y., Roldugin D.S., Ivanov D.S., Penkov V.I. *Acta Astronautica*, 2015, vol. 116, pp. 74–77.
- [10] Ovchinnikov M.Y., Penkov V.I., Roldugin D.S., Ivanov D.S. *Magnitnye sistemy orientatsii malykh sputnikov* [Magnetic systems for small satellite orientation]. Moscow, Keldysh Institute of Applied Mathematics Publ., 2016, 366 p.
- [11] Ivanov D.S., Ovchinnikov M.Yu., Penkov V.I., Ovchinnikov A.V. *Acta Astronautica*, 2016, vol. 132, pp. 103–110.

- [12] Beletsky V.V. *Dvizhenie sputnika otnositelno tsentra mass v gravitatsionnom pole* [The satellite motion relative to the center of mass in the gravitational field]. Moscow, MSU Publ., 1975, 308 p.
- [13] Kalenova V.I., Morozov V.M. *Lineynye nestatsionarnye sistemy i ikh prilozheniya k zadacham mekhaniki* [Linear nonstationary systems and their applications to problems of mechanics]. Moscow, Fizmatlit Publ., 2010, 208 p.
- [14] Kalenova V.I., Morozov V.M. *Prikladnaya matematika i mekhanika — Journal of Applied Mathematics and Mechanics*, 2012, vol. 76, no. 4, pp. 576–588.
- [15] Kalenova V.I., Morozov V.M. *Izvestiya RAN. Teoriya i sistemy upravleniya — Journal of Computer and Systems Sciences International*, 2013, no 3, pp. 6–15.
- [16] Morozov V.M., Kalenova V.I. Linear time-varying systems and their applications to cosmic problems. *AIP Conference Proceedings*, 2018, vol. 1959, pp. 020–003.
- [17] Bellman R. *Introduction to matrix analysis*. NY, Toronto, London, McGraw-Hill Book Company, Inc. Publ., 1960, 348 p. [In Russ.: Bellman R. *Vvedenie v teoriyu matrix*. Moscow, Nauka Publ., 1969, 368 p.].
- [18] Laub A.J., Arnold W.F. *IEEE Transaction on Automatic Control*, 1984, vol. AC-29, no. 2, pp. 163–165.

Morozov V.M., Dr. Sc. (Phys.-Math.), Professor, Senior Research Fellow, Institute of Mechanics, Lomonosov Moscow State University. e-mail: moroz@imec.msu.ru

Kalenova V.I., Cand. Sc. (Phys.-Math.), Leading Research Fellow, Institute of Mechanics, Lomonosov Moscow State University. e-mail: kalen@imec.msu.ru